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(54) GAS VALVE WITH HIGH SPEED OPENING AND HIGH SPEED GAS FLOW CAPABILITY

GASVENTIL MIT HOCHGESCHWINDIGKEITSÖFFNUNG UND
HOCHGESCHWINDIGKEITSGASFLUSSKAPAZITÄT

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Description

TECHNICAL FIELD

[0001] The invention relates to gas valves with high speed opening and high speed gas flow capability.

BACKGROUND ART

[0002] Gas valves with high speed opening and high speed gas flow capability are required for various uses, for example in cold gas airbag inflation test systems for testing automobile airbags that protect occupants of the automobile in the event of a collision. Specifically, airbag deployment systems basically include an airbag and an inflator. The inflator generates and releases the gas necessary to inflate the airbag. During a collision in an automobile, the inflator is triggered by the destruction of a rupture disc, which releases the gas to fill the airbag in a mere fraction of a second.

[0003] Even a small change in the orientation of a vehicle's dash board could have a significant effect on the deployment of an airbag since the deployment occurs so quickly. As a result, many tests must be performed throughout the design or re-design process of an automobile to ensure that the deployment of the airbags meet all regulations or requirements. The rupture discs are permanently destroyed in automobile airbag systems so the airbags must be completely replaced after use. It is therefore not feasible to use actual airbag systems to run large numbers of tests while designing a vehicle.

[0004] Instead, a separate, re-usable valve apparatus is desired to simulate the destruction of the rupture disc and subsequent inflation of the airbag. Such a valve must perform consistently and accurately so that it does not skew data being collected or introduce error into the tests. These valves must also deploy extremely quickly to properly simulate actual airbag deployment. A typical simulation gas valve inflator, for example, may need to consistently open a one inch diameter valve in 2ms. At the present time, suitable gas valves for this purpose do not appear to be commercially available which can properly simulate actual airbag deployment in a nondestructive manner.

[0005] For example, United States Patent No. 4,635,855 (Kuyel et al.) teaches a method and apparatus for rapidly controlling a flow of gas which utilizes a conductive disc to seal an orifice of a plenum holding the gas, and an electrode located proximate to the plate. By applying a current through the electrode, an eddy current is induced in the disc, which creates a repulsion force that repels the disc away from the electrode for opening the orifice. However, to open the orifice, the repulsion force must overcome a force due to pressure of the gas stored in the plenum, and therefore, is too slow and inconsistent to be used in an airbag deployment simulation. Furthermore, the apparatus taught in this reference would open even slower, or perhaps not at all, when used

with gases having significantly high pressures, as the repulsion force would have to be incredibly high to overcome the force due to pressure.

[0006] Similarly, Japanese Patent Publication No. JP58191380 (Kazuo) teaches a gas valve which utilizes induced eddy currents in a plate coupled to a rod to open or close the valve by varying the current passing through permanent magnets located proximate to the plate. Like the '855 patent to Kuyel et al., the system taught in this reference must overcome a force on the plate due to a pressure of the gas, and therefore, is too slow and inconsistent to be used to test airbag deployment. Also like the Kuyel et al. apparatus, the system taught in this reference would open even slower, or perhaps not at all, when used with gases having significantly high pressures, as the repulsion force would have to be incredibly high to overcome the force due to pressure.

[0007] The US patent US 3,785,612 discloses a quick acting valve apparatus according to the preamble of claim 1. A piston is moveable in a casing and separating an upper chamber from a lower chamber within the casing. The piston contains an electromagnet. When pressurized air from the upper chamber is allowed to escape to the atmosphere, pressurized air in the lower chamber moves the piston upwards. Therein the electromagnet attracts a holding plate connected to a valve disc via a stem, thus raising the valve disc, opening the valve. For some applications the opening speed of this valve is not sufficient.

[0008] It is therefore an object of the invention to provide a gas valve which is capable of high speed opening and high speed gas flow and is also suitable for use in a cold gas airbag test system.

DISCLOSURE OF INVENTION

[0009] The present invention broadly comprises a high speed gas valve apparatus including a reservoir for holding a gas having a charge port for filling the reservoir with the gas and an outlet for releasing the gas from the reservoir, a rod slidably housed in the valve apparatus, the rod including a sealing means operatively arranged to engage with the outlet of the valve chamber for sealing the reservoir when the valve is in a closed position, a pneumatic actuator, wherein a piston of the pneumatic actuator is coupled to the rod, an electro-magnetic actuator coupled to the rod, and wherein the gas is released from the reservoir via the outlet when the apparatus is in an open position, and the valve transitions from the closed position to the open position by activating the pneumatic and electro-magnetic actuators to move the rod away from the outlet.

[0010] According to the invention the valve apparatus further includes a first chamber and a second chamber located on opposite sides of the piston of the pneumatic actuator, wherein the gas in the reservoir has a first pressure that exerts a first force on the rod in a first direction for maintaining the valve in the closed position by forcing

the sealing means of the rod to remain engaged with the outlet, wherein a second pressure in the first chamber exerts a second force on the piston in the first direction for forcing the sealing means of the rod to engage with the outlet, wherein a third pressure in the second chamber exerts a third force on the piston in a second direction, wherein the second direction is opposite from the first direction, and wherein subsequent to an activation of the pneumatic actuator, but preceding an activation of the electro-magnetic actuator, a sum of the first and second forces is greater than the third force.

[0011] In an embodiment, the third force is slightly less than the sum of the first and second forces for substantially reducing a net force required by the electro-magnetic actuator to transition the valve from the closed position into the open position.

[0012] In another embodiment, the electro-magnetic actuator comprises an electronic coil and an electrically conductive plate, wherein the plate is fixedly secured to the rod and located proximate to the coil when the valve is in the closed position, wherein the coil is electronically connected to a capacitor, wherein the electro-magnetic actuator is activated by discharging a current from the capacitor through the coil for creating a first magnetic field, wherein the first magnetic field induces a second magnetic field in the plate, and the second magnetic field is oppositely polarized with respect to the first magnetic field, wherein a repulsion force is created due to the first and second magnetic fields being oppositely polarized, and the repulsion force repels the plate away from the coil for transitioning the valve from the closed position to the open position by moving the rod away from the outlet.

[0013] The current invention also broadly comprises a method of operating a gas valve comprising the steps of: (a) pressurizing a first chamber in a pneumatic actuator, wherein a second pressure in the first chamber exerts a second force in a first direction on a piston of the pneumatic actuator, wherein the piston is coupled to a rod, for entering the valve into a closed position by forcing the rod to engage with an outlet of a reservoir of the gas valve; (b) pressurizing a reservoir of the gas valve with a gas having a first pressure; (c) depressurizing the first chamber in the pneumatic actuator for reducing the second pressure and the second force, wherein the gas in the reservoir exerts a first force due to the first pressure in the first direction on the piston for maintaining the valve in the closed position by forcing the rod to stay engaged with the outlet; (d) pressurizing a second chamber in the pneumatic actuator located on an opposite side of the piston from the first chamber, wherein a third pressure in the second chamber exerts a third force on the piston in a second direction opposite from the first direction of the first and second forces, wherein the piston transfers the third force to the rod, and wherein a sum of the first and second forces is larger than the third force; and, (e) activating an electro-magnetic actuator coupled to the rod for releasing the gas from the reservoir by transitioning the valve from the closed position to an open position

by moving the rod away from the outlet.

[0014] In one embodiment, subsequent to step (d), but prior to step (e), the third force is slightly less than the sum of the first and second forces for substantially reducing a net force required by the electro-magnetic actuator to transitioning the valve into the open position. In another embodiment, activating the electro-magnetic actuator in step (e) further comprises discharging a current through an electronic coil for creating a first magnetic field, wherein the electronic coil is located proximate to a plate which is fixedly secured to the rod, wherein the first magnetic field induces a second magnetic field in the plate, and the second magnetic field is polarized oppositely with respect to the first magnetic field, wherein a repulsion force is created due to the first and second magnetic fields being oppositely polarized, and the repulsion force repels the plate from the coil for transitioning the valve from the closed position to the open position by forcing the rod away from the outlet.

[0015] These and other objects and advantages of the present invention will be readily appreciable from the following description of preferred embodiments of the invention and from the accompanying drawings and claims.

BRIEF DESCRIPTION OF DRAWINGS

[0016] The nature and mode of operation of the present invention will now be more fully described in the following detailed description of the invention taken with the accompanying drawing figures, in which:

Figure 1 is a partial cross-sectional side view of a gas valve according to the current invention;

Figure 2a is a schematic of a circuit for operating the electro-magnetic actuator of the gas valve shown in Figure 1;

Figure 2b is a relevant portion of the schematic shown in Figure 2a with the switch open;

Figure 2c is a relevant portion of the schematic shown in Figure 2a with the switch closed; and,

Figures 3-9 are cross-sectional views of the gas valve shown in Figure 1 incrementally illustrating operation of the gas valve.

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BEST MODE FOR CARRYING OUT THE INVENTION

[0017] At the outset, it should be appreciated that like drawing numbers on different drawing views identify identical, or functionally similar, structural elements of the invention. While the present invention is described with respect to what is presently considered to be the preferred aspects, it is to be understood that the invention as claimed is not limited to the disclosed aspects.

[0018] Furthermore, it is understood that this invention is not limited to the particular methodology, materials and modifications described and as such may, of course, vary. It is also understood that the terminology used here-

in is for the purpose of describing particular aspects only, and is not intended to limit the scope of the present invention, which is limited only by the appended claims.

[0019] Unless defined otherwise, all technical and scientific terms used herein have the same meaning as commonly understood to one of ordinary skill in the art to which this invention belongs. Although any methods, devices or materials similar or equivalent to those described herein can be used in the practice or testing of the invention, the preferred methods, devices, and materials are now described.

[0020] Referring now to the Figures, Figure 1 illustrates high speed gas valve 10, according to the current invention. Gas valve 10 includes valve body 12 that defines valve chamber or reservoir 14, which includes auxiliary inlet 16, outlet 18, and valve charge port 19. Auxiliary charge vessel 20 is detachably securable to inlet 16 and orifice bar 22 is detachably securable proximate to outlet 18.

[0021] Since reservoir 14 is a fixed volume, auxiliary charge vessel 20 is attached to reservoir 14 so that the volume of gas that valve 10 can hold is variably changeable. For example, if the reservoir has a volume of 1 L, auxiliary vessels of .5L, .75L, or 1 L could be attached via inlet 16 to increase the volume of gas in valve apparatus 10 to 1.5L, 1.75L, and 2L, respectively. Orifice bar 22 includes a hole that is aligned with outlet 18 for determining the flow characteristics of gas released from chamber 14 via outlet 18. For example, it may be desirable to increase or decrease the exit velocity or mass flow rate of the gas from the outlet by varying the size of the hole in the orifice bar.

[0022] Valve sealing member 24 which includes valve sealing ring 25 is included on one end of rod 26. The rod is slidingly movable within the valve apparatus for selectively sealing and opening outlet 18. That is, valve closure member 24, which resembles a large bulb on the end of rod 26, is pressed into outlet 18 to create an airtight seal with the aid of sealing ring 25. Thus, the sealing member alone or together with the sealing ring comprises a sealing means for the valve. Sealing ring 25 is preferably a flexible and resilient o-ring fabricated from any number of polymers or other suitable materials. A second end of rod 26, opposite from valve sealing member 24, extends into housing 30, which is secured to valve body 12. Housing 30 is preferably fixed to an immobile object via mount 31, which may use bolts (not shown) or some other means known in the art to secure valve 10 in place. The second end of rod 26 is affixed to piston 32, which is slidingly mounted within cylinder 34, which in turn is mounted in housing 30. Piston 32 and cylinder 34 are components of pneumatic actuator 36, which may be any pneumatic actuator known in the art, including those that are commonly available commercially, but which preferably takes the general form shown in the Figures and described herein.

[0023] Plate 40 is mounted to an intermediate portion of rod 26 between sealing member 24 and pneumatic

actuator 36. The disc is located adjacent to electrical coil L₁ when the valve is in a closed position. By closed position we mean that sealing means 24 on rod 26 is engaged in a sealed relation with outlet 18 so that no gas stored in reservoir 14 can escape the reservoir through the outlet. The coil is fixedly mounted to housing 30 so that it is immovable with respect to valve 10. Plate 40 and coil L₁ are components of electro-magnetic actuator 44.

[0024] A preferred embodiment of main circuit 46 for electro-magnetic actuator 44 is shown schematically in Figure 2A. The circuit includes coil L₁, high voltage power source V_H, capacitor C₁, resistors R₁ and R₂, diode D₁, silicon-controlled rectifier SCR₁, switch S₁, optocoupler OC, control circuit 48 and low voltage source V_L. High voltage supply V_H is used to charge capacitor C₁, which stores the energy dissipated by the high voltage power source. Silicon-controlled rectifier SCR₁ acts as a high-speed switch for delivering the energy from capacitor C₁ to coil L₁. Diode D₁ is connected across coil L₁ to protect the other components of the circuit from the back EMF generated by the rapid collapsing magnetic field in the coil. Optocoupler OC electronically isolates control circuit 48 and sends signals in the form of light or optics from the control circuit to operate main circuit 46. Control circuit 48 may send signals via the optocoupler to open and close switch S₁ or turn the SCR on and off, for example. Low voltage power supply V_L provides a low voltage to the gate of the SCR to enable the SCR to operate. The resistance of resistor R₂ is chosen to regulate the voltage that is applied to gate G, as is well known to those having ordinary skill in the art of circuit design.

[0025] Figures 2B and 2C show a schematic of the relevant portion of circuit 46 and plate 40 when switch S₁ is opened and closed, respectively. When switch S₁ is open no current passes through the coil. When switch S₁ is closed, as in Figure 2C, large currents (several hundred amperes, for example) are generated because of the high voltage and capacitance, and extremely short discharge time of the capacitor, causing the coil to produce a powerful increasing magnetic field 42a, which passes through plate 40. While passing through the plate, magnetic field 42a induces eddy currents 50 in the direction indicated by arrow 52, which is opposite to the direction of current through the coil, as indicated by arrow 54. The induced current in plate 40 generates magnetic field 40a oppositely polarized with respect to magnetic field 42a, as fields 40a and 42a act generally in the direction of arrows 58 and 56, respectively. The two oppositely polarized magnetic fields generate a large repulsive force between the coil and the plate. The coil cannot move, as it is fixedly secured to housing 30 which is immovably anchored by valve mount 31. Consequently, the repulsive force rapidly repels plate 40 from coil L₁. Since the plate is fixedly secured to the rod, the plate and the rod are forced in direction 58 away from outlet 18, to open outlet of valve 10.

[0026] The following describes the parameters of a

preferred embodiment of circuit **46**, as shown in Figure 2, but it should be understood that the circuit could have other parameters readily recognizable by one skilled in the art. In order to maximize the energy transfer between the coil and the plate, the values of the capacitance, inductance and resistance should be chosen such that they create a critically damped circuit. Further, the below embodiment is designed to produce approximately a 2670 N (600 lb) force for 200 μ s between plate **40** and coil **L**₁, with the total energy being dissipated in about 500 μ s. In this embodiment, coil **L**₁ has an inductance of approximately 2mH, high voltage power source **V**_H is a 2000VDC, 60mA power supply, capacitor **C** has a capacitance of 150 μ F, resistor **R**₁ is achieved by approximately 1Ω of inherent wire resistance so that an actual resistor is not used, and low voltage source **V**_L is a 24VDC power supply. The overall length of the coil should be kept to a minimum and the plate should be kept as close to the coil as possible. In order to reduce the length of the wire used to make coil **L**₁ and to maintain the physical soundness of the coil, ribbon wire is preferably used instead of traditional magnetic wire. In the preferred embodiment, plate **40** is made of aluminum because it is lightweight and produces a sufficient magnetic field. Steel plates tend to be heavy and may occasionally become magnetically attracted to the coil. In this preferred embodiment, the coil and plate are pressed together, separated by only a thin sheet of plastic. It should be appreciated that the circuit elements and their associated values recited above are illustrative only, and that circuits having elements with different values can easily be configured by one having ordinary skill in the art of circuit design.

[0027] The valve is shown in an initial, open state in a cross-sectional view in Figure 3. By open we mean that sealing member **24** on rod **26** is not in a sealed relation with outlet **18** so that gas can freely escape the outlet from reservoir **14**. Pneumatic actuator **36** includes chambers **60** and **62** on opposite sides of piston **32** in cylinder **34**. Chamber **60** cannot be seen in Figure 3 as the piston is pushed to the far right side of the cylinder, leaving no room for chamber **60**. Pressures **P**₁, **P**₂, and **P**₃ represent the pressures in chambers **14**, **60**, and **62**, respectively. In the initial state as shown in this Figure, all of the pressures are substantially equal to the atmospheric pressure, and the system is therefore balanced and in equilibrium. By atmospheric pressure we mean the pressure of the room or area in which valve **10** is housed. It should be appreciated that when pressures **P**₁, **P**₂, and **P**₃ are discussed in relative terms, or as gauge pressures, atmospheric pressure is assumed to be zero or no pressure. Therefore, a chamber at atmospheric pressure is assumed to exert no forces on the chamber or objects in the chamber, such as the rod.

[0028] Valve **10** is shown in a closed position in Figure 4. By closed position we mean that sealing member **24** engages outlet **18** for making reservoir **14** airtight. An activation of pneumatic actuator **36** forces rod **26** into the

closed position shown. Specifically, the activation of pneumatic actuator **36** comprises pressurizing chamber **60** so that pressure **P**₂ is high enough to exert a force to move piston **32**, and therefore rod **26** and sealing member **24**, towards outlet **18**. In a preferred embodiment, pressure **P**₂ is about 172 kPa (25 psig). As shown in Figure 5, reservoir **14** is filled with a high pressure gas having pressure **P**₁ via charge port **19** as indicated by arrow **64**.

In the preferred embodiment, pressure **P**₁ is about 20,7 MPa (3000 psig) but it could be other pressures, as desired. If auxiliary vessel **20** is present, the gas from charge port **19** will also fill the charge vessel, which is initially empty. Pressures **P**₁ and **P**₂ exert first and second forces on rod **26** (indirectly through piston **32** and sealing member **24**, respectively) in the direction indicated by arrow **56** toward the outlet.

[0029] Next, chamber **60** is depressurized so that pressure **P**₂ returns to approximately atmospheric pressure, as shown in Figure 6. However, rod **26** is held in sealed engagement with the outlet due to pressure **P**₁ exerting a force on sealing member **24** of the rod. In this Figure, the valve reservoir is storing the gas that is desired to be released when the outlet is opened, such as, for example, the gas necessary to fill an airbag in an airbag inflation test. It may be desirable to leave pressure **P**₂ at a relatively low value, such as 70 kPa (10 psig) so that it can cushion the cylinder from the piston when electro-magnetic actuator **44** is fired, as will be described later.

[0030] As shown in Figure 7, chamber **62** is then pressurized so that it contains pressure **P**₃. Pressure **P**₃ exerts a third force in the direction of arrow **58** on piston **32**, which transfers the third force to rod **26** and sealing member **24**. Pressure **P**₃ is preferably increased to a point at which outlet **18** is just about to open, but at which the outlet is still completely sealed. That is, the magnitude of the force due to pressure **P**₃ in direction **58** is just less than a sum of the forces due to pressures **P**₁ and **P**₂ in direction **56**. In the preferred embodiment, pressure **P**₃ varies between approximately 172-862 kPa (25-125 psig) during this phase.

[0031] It is well known that the force exerted on a surface of a chamber is equal to the pressure in the chamber multiplied by the area of the surface. Therefore, by including a surface area of piston **32** on which pressure **P**₃ acts which is substantially greater than the surface area of sealing member **24** on which pressure **P**₁ acts, as shown in the Figures, it is possible to exert a force in direction **58** equal to a force in direction **56** with a substantially smaller pressure **P**₃ with respect to pressure **P**₁. Thus, in the preferred embodiment, when pressure **P**₁ is 20,7 MPa (3000 psig) pressure **P**₃ only has to be about 862 kPa (125 psig) to exert a force to sufficiently counteract the force exerted by pressure **P**₁.

[0032] If pressure **P**₃ were increased enough, so that the force in the direction of arrow **58** were higher than force due to pressure **P**₁ in the direction of arrow **56**, the rod would be forced to move in direction **58**, thereby opening outlet **18** by breaking the sealed engagement of

the sealing member and the outlet. However, for many applications, particularly for testing the inflation of airbags, an entirely pneumatic valve would open the valve too slowly, and would also result in inconsistent opening times for the valve in repeated trials. Obviously, if valve 10 were used in a testing scenario, the valve must work consistently and quickly to properly simulate the same deployment speed as a real airbag.

[0033] Instead of increasing pressure P_3 further, pressure P_3 is held so that the forces exerted by pressure P_3 is just less than the sum of the forces exerted by pressures P_1 and P_2 . That is, the outlet requires only a small amount of force to open, but the outlet is still completely sealed by the sealing member of the rod. For example, if the third force equaled ninety percent of the sum of the first and second forces, the electro-magnetic actuator would only have to overcome ten percent of the sum of the first and second forces to open the valve. As such, P_3 could be tuned with respect to pressures P_1 and P_2 for varying the opening speed of the valve.

[0034] At the stage shown in Figure 9, the pneumatic actuator has completed its activation and electro-magnetic actuator 44 is fired. Pressure P_3 counteracts the force due to pressure P_1 , so that the electro-magnetic actuator has a substantially reduced force to overcome to open the outlet. That is, if pressure P_3 were not present, the electro-magnetic actuator would have to overcome a larger force in opening the outlet, which would result in a slower opening of valve 10. Moreover, by including an appropriate pressure P_3 , one can quickly and consistently open valve 10 regardless of pressure P_1 of the gas stored in reservoir 14.

[0035] As discussed with respect to Figures 2a-2c, the activation of electro-magnetic actuator 44 creates powerful oppositely polarized magnetic fields which repel plate 40 from coil L. Since rod 26 is slidingly housed in housing 30 and plate 40 is fixedly secured to the rod, the repulsion of the plate from coil also moves the rod away from the outlet. If circuit 45 has the parameters described in the preferred embodiment above, the rod is repelled forcefully away from outlet 18, opening a one inch diameter outlet in about 2ms. Advantageously, as soon as the outlet is cracked open, pressure P_1 surrounds and acts on the front of sealing member 24 to help open the outlet by pushing the rod in direction 58. Once the outlet is opened, the high pressure gas is released from reservoir 14 (and auxiliary vessel 20, if present) as indicated by arrow 66.

[0036] It should be appreciated that one could use valve 10 to do more than just inflate airbags for testing. For example, it has been conceived that one could use different nozzles on the end of valve 10 to produce and examine shockwaves or special gas flows, such as supersonic flows, in physiological or materials research. Additionally, one could choose to elongate rod 26 to extend out of the back of cylinder 34, for example, to use rod 26 as a ram, punch, plunger, impacting device, or launching means for a projectile, to name but a few pos-

sible applications.

Claims

- 5 1. A high speed gas valve apparatus (10) comprising:
 a reservoir (14) for holding a gas having a charge port (19) for filling said reservoir (14) with said gas and an outlet (18) for releasing said gas from said reservoir (14);
 a rod (26) slidably housed in said valve apparatus (10), said rod (26) including a sealing means operatively arranged to engage said outlet (18) of said reservoir (14) for sealing said reservoir (14) when said valve apparatus (10) is in a closed position;
 a pneumatic actuator (36), wherein a piston (32) of said pneumatic actuator (36) is coupled to said rod (26);
 a first chamber (60) and a second chamber (62) located on opposite sides of said piston (32) in said pneumatic actuator (36);
 wherein said gas in said reservoir (14) has a first pressure (P1) that exerts a first force on said rod (26) via said sealing means in a first direction (56) for maintaining said valve (10) in said closed position by forcing said sealing means of said rod (26) to remain engaged with said outlet (18);
 wherein a second pressure (P2) in said first chamber (60) exerts a second force on said piston (32) in said first direction (56) for forcing said sealing means of said rod (26) to engage with said outlet (18);
 wherein a third pressure (P3) in said second chamber (62) exerts a third force on said piston (32) in a second direction (58), wherein said second direction (58) is opposite from said first direction (56), and
 an electro-magnetic actuator (44) coupled to said rod (26); wherein said gas is released from said reservoir (14) via said outlet (18) when said valve apparatus (10) is in an open position, and said valve (10) transitions from said closed position to said open position by sequentially activating said pneumatic (36) and electro-magnetic (44) actuators to move said rod (26) away from said outlet (18);

characterized in that

subsequent to an activation of said pneumatic actuator (36), but preceding an activation of said electro-magnetic actuator (44), a sum of said first and second forces is greater than said third force.

- 50 55 2. The gas valve apparatus (10) recited in claim 1 wherein said third force is slightly less than said sum of said first and second forces for substantially re-

ducing a net force required by said electro-magnetic actuator (44) to transition said valve (10) from said closed position into said open position.

3. The gas valve apparatus (10) recited in claim 1 wherein said electro-magnetic actuator (44) comprises:

an electronic coil (L1) electrically coupled in a circuit (46) to a high voltage power supply (VH) and a capacitor (C1);
 an electrically conductive plate (40) fixedly secured to said rod (26) and located proximate said coil (L1) when said valve (10) is in said closed position; and,
 wherein said electro-magnetic actuator (44) is activated by discharging a current from said capacitor (C1) through said coil (L1) for generating a first magnetic field in said coil (L1), wherein said first magnetic field induces eddy currents in said plate (40), wherein said eddy currents generate a second magnetic field, and said second magnetic field is oppositely polarized with respect to said first magnetic field, wherein a repulsion force is created due to said first and second magnetic fields being oppositely polarized, and said repulsion force repels said plate (40) away from said coil (L1) for transitioning said valve (10) from said closed position to said open position by moving said rod (26) away from said outlet (18).
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4. The gas valve apparatus (10) recited in claim 3 wherein said plate (40) is aluminum.
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5. The gas valve apparatus (10) recited in claim 3 wherein said coil (L1) is fabricated from ribbon wire.
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6. The gas valve apparatus (10) recited in claim 3 wherein said high voltage power source (VH) applies a voltage of approximately 2000V, said capacitor (C1) has a capacitance of approximately 150pF, said coil (L1) has an inductance of approximately 2mH and said circuit (46) has a total resistance of approximately 1Ω.
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7. The gas valve apparatus (10) recited in claim 3 wherein said high voltage power source (VH), said capacitor (C1), and said coil (L1) comprise a critically damped RLC circuit.
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8. The gas valve apparatus (10) recited in claim 3 wherein said plate (40) is pressed against said coil (L1) when said valve apparatus (10) is in said closed position.
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9. The gas valve apparatus (10) recited in claim 8 wherein a thin layer of nonconductive material is

sandwiched between said coil (L1) and said plate (40) when said coil (L1) and said plate (40) are pressed together.

- 5 10. A method of operating a gas valve (10) comprising the steps of:

(a) pressurizing a first chamber (60) in a pneumatic actuator (36), wherein a second pressure (P2) in said first chamber (60) exerts a second force in a first direction (56) on a piston (32) of said pneumatic actuator (36), wherein said piston (32) is coupled to a rod (26), for entering said valve (10) into a closed position by forcing said rod (26) to engage with an outlet (18) of a reservoir (14) of said gas valve (10);
 (b) pressurizing a reservoir (14) of said gas valve (10) with a gas having a first pressure (P1);
 (c) depressurizing said first chamber (60) in said pneumatic actuator (36) for reducing said second pressure (P2) and said second force, wherein said gas in said reservoir (14) exerts a first force due to said first pressure (P1) in said first direction (56) on said piston (32) for maintaining said valve (10) in said closed position by forcing said rod (26) to stay engaged with said outlet (18);
 (d) pressurizing a second chamber (62) in said pneumatic actuator (36) located on an opposite side of said piston (32) from said first chamber (60), wherein a third pressure (P3) in said second chamber (62) exerts a third force on said piston (32) in a second direction (58) opposite from said first direction (56) of said first and second forces, wherein said piston (32) transfers said third force to said rod (26), and wherein a sum of said first and second forces is larger than said third force; and,
 (e) activating an electro-magnetic actuator (44) coupled to said rod (26) for releasing said gas from said reservoir (14) by transitioning said valve (10) from said closed position to an open position by moving said rod (26) away from said outlet (18).
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11. The method of operating a gas valve (10) as recited in claim 10 wherein subsequent to step (d), but prior to step (e), said third force is slightly less than said sum of said first and second forces for substantially reducing a net force required by said electro-magnetic actuator (44) to transitioning said valve (10) into said open position.
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12. The method of operating a gas valve (10) as recited in claim 11 wherein activating said electro-magnetic actuator (44) in step (e) further comprises discharging a current through an electronic coil (L1) for creating a first magnetic field, wherein said electronic

coil (L1) is located proximate a plate (40) which is fixedly secured to said rod (26), wherein said first magnetic field induces eddy currents in said plate (40), and said eddy currents generate a second magnetic field, and said second magnetic field is polarized oppositely with respect to said first magnetic field, wherein a repulsion force is created due to said first and second magnetic fields being oppositely polarized, and said repulsion force repels said plate (40) from said coil (L1) for transitioning said valve (10) from said closed position to said open position by forcing said rod (26) away from said outlet (18).

Patentansprüche

- Hochgeschwindigkeits-Gasventilvorrichtung (10), umfassend:

ein Reservoir (14) zum Aufnehmen eines Gases, umfassend eine Einlassöffnung (19) zum Füllen des Reservoirs (14) mit dem Gas und einen Auslass (18) zum Freisetzen des Gases aus dem Reservoir (14);

eine Stange (26), die gleitbar in der Ventilvorrichtung (10) untergebracht ist, wobei die Stange (26) ein Dichtmittel umfasst, das operativ derart angeordnet ist, dass es in Eingriff mit dem Auslass (18) des Reservoirs (14) gelangt, um das Reservoir (14) abzudichten, wenn sich die Ventilvorrichtung (10) in einer geschlossenen Stellung befindet;

einen pneumatischen Aktuator (36), wobei ein Kolben (32) des pneumatischen Aktuators (36) mit der Stange (26) gekoppelt ist;

eine erste Kammer (60) und eine zweite Kammer (62), die an entgegengesetzten Seiten des Kolbens (32) im pneumatischen Aktuator (36) angeordnet sind;

wobei das Gas in dem Reservoir (14) einen ersten Druck (P1) aufweist, der über das Dichtmittel in einer ersten Richtung (56) eine erste Kraft auf die Stange (26) ausübt, um das Ventil (10) in der geschlossenen Stellung zu halten, indem das Dichtmittel der Stange (26) gezwungen wird, in Eingriff mit dem Auslass (18) zu bleiben;

wobei ein zweiter Druck (P2) in der ersten Kammer (60) auf den Kolben (32) eine zweite Kraft in der ersten Richtung (56) ausübt, um das Dichtmittel der Stange (26) zu zwingen, in Eingriff mit dem Auslass (18) zu gelangen;

wobei ein dritter Druck (P3) in der zweiten Kammer (62) auf den Kolben (32) eine dritte Kraft in einer zweiten Richtung (58) ausübt, wobei die zweite Richtung (58) entgegengesetzt zur ersten Richtung (56) ist; und

einen elektromagnetischen Aktuator (44), der mit der Stange (26) gekoppelt ist;

wobei das Gas durch den Auslass (18) aus dem Reservoir (14) freigesetzt wird, wenn sich die Ventilvorrichtung (10) in einer geöffneten Stellung befindet, und wobei das Ventil (10) von der geschlossenen Stellung in die geöffnete Stellung übergeht, indem der pneumatische Aktuator (36) und der elektromagnetische Aktuator (44) nacheinander aktiviert werden, um die Stange (26) vom Auslass (18) wegzbewegen;

dadurch gekennzeichnet, dass

nach einer Aktivierung des pneumatischen Aktuators (36), aber vor einer Aktivierung des elektromagnetischen Aktuators (44) eine Summe der ersten und zweiten Kräfte größer als die dritte Kraft ist.

- Gasventilvorrichtung (10) nach Anspruch 1, wobei die dritte Kraft etwas geringer als die Summe der ersten und zweiten Kräfte ist, um eine Nettokraft wesentlich zu senken, die vom elektromagnetischen Aktuator (44) benötigt wird, um das Ventil (10) von der geschlossenen Stellung in die geöffnete Stellung zu bewegen.
- Gasventilvorrichtung (10) nach Anspruch 1, wobei der elektromagnetische Aktuator (44) umfasst:

eine elektronische Spule (L1), die in einem Schaltkreis (46) mit einer Hochspannungs-Stromversorgung (VH) und einem Kondensator (C1) elektrisch verbunden ist;

eine elektrisch leitende Platte (40), die mit der Stange (26) fest verbunden ist und in der Nähe der Spule (L1) angeordnet ist, wenn sich das Ventil (10) in der geschlossenen Stellung befindet; und

wobei der elektromagnetische Aktuator (44) aktiviert wird, indem ein Strom von dem Kondensator (C1) durch die Spule (L1) entladen wird, um ein erstes Magnetfeld in der Spule (L1) zu erzeugen, wobei das erste Magnetfeld Wirbelströme in der Platte (40) induziert, wobei die Wirbelströme ein zweites Magnetfeld erzeugen, und wobei das zweite Magnetfeld bezüglich des ersten Magnetfelds entgegengesetzt polarisiert ist, wobei dadurch, dass die ersten und zweiten Magnetfelder entgegengesetzt polarisiert sind, eine Abstoßungskraft erzeugt wird, und wobei die Abstoßungskraft die Platte (40) von der Spule (L1) wegdrückt, um das Ventil (10) von der geschlossenen Stellung in die geöffnete Stellung zu bringen, indem die Stange (26) vom Auslass (18) wegbewegt wird.

- Gasventilvorrichtung (10) nach Anspruch 3, wobei die Platte (40) Aluminium ist.
- Gasventilvorrichtung (10) nach Anspruch 3, wobei

- die Spule (L1) aus Flachdraht bzw. Banddraht hergestellt ist.
6. Gasventilvorrichtung (10) nach Anspruch 3, wobei die Hochspannungs-Stromquelle (VH) eine Spannung von etwa 2000V bereitstellt, wobei der Kondensator (C1) eine Kapazität von etwa 150 pF aufweist, wobei die Spule (L1) eine Induktivität von etwa 2mH aufweist und wobei der Schaltkreis (46) einen Gesamtwiderstand von etwa 1Ω aufweist. 5
7. Gasventilvorrichtung (10) nach Anspruch 3, wobei die Hochspannungs-Stromquelle (VH), der Kondensator (C1) und die Spule (L1) einen kritisch gedämpften RLC-Schaltkreis umfassen. 10
8. Gasventilvorrichtung (10) nach Anspruch 3, wobei die Platte (40) gegen die Spule (L1) gedrückt wird, wenn sich die Ventilvorrichtung (10) in der geschlossenen Stellung befindet. 15
9. Gasventilvorrichtung (10) nach Anspruch 8, wobei eine dünne Schicht aus einem nichtleitenden Material zwischen der Spule (L1) und der Platte (40) eingeklemmt angeordnet ist, wenn die Spule (L1) und die Platte (40) zusammengedrückt werden. 20
10. Verfahren zum Betreiben eines Gasventils (10), umfassend die folgenden Schritte: 25
- (a) Druckbeaufschlagung einer ersten Kammer (60) in einem pneumatischen Aktuator (36), wobei ein zweiter Druck (P2) in der ersten Kammer (60) eine zweite Kraft in einer ersten Richtung (56) auf einen Kolben (32) des pneumatischen Aktuators (36) ausübt, wobei der Kolben (32) mit einer Stange (26) gekoppelt ist, um das Ventil (10) in eine geschlossene Stellung zu bringen, indem die Stange (26) gezwungen wird, in Eingriff mit einem Auslass (18) eines Reservoirs (14) des Gasventils (10) zu gelangen; 30
 - (b) Druckbeaufschlagung eines Reservoirs (14) des Gasventils (10) mit einem Gas, das einen ersten Druck (P1) aufweist; 35
 - (c) Druckentlastung der ersten Kammer (60) im pneumatischen Aktuator (36), um den zweiten Druck (P2) und die zweite Kraft zu vermindern, wobei das Gas in dem Reservoir (14) eine erste Kraft ausübt, und zwar aufgrund des ersten Drucks (P1) auf den Kolben (32) in der ersten Richtung (56), um das Ventil (10) in der geschlossenen Stellung zu halten, indem die Stange (26) gezwungen wird, in Eingriff mit dem Auslass (18) zu bleiben; 40
 - (d) Druckbeaufschlagung einer zweiten Kammer (62) im pneumatischen Aktuator (36), der an einer Seite des Kolbens (32) angeordnet ist, die jener der ersten Kammer (60) entgegengesetzt ist, wobei ein dritter Druck (P3) in der zweiten Kammer (62) eine dritte Kraft auf den Kolben (32) in einer zweiten Richtung (58) ausübt, die in Bezug auf die erste Richtung (56) der ersten und zweiten Kräfte entgegengesetzt ist, wobei der Kolben (32) die dritte Kraft auf die Stange (26) überträgt und wobei eine Summe der ersten und zweiten Kräfte größer als die dritte Kraft ist; und 45
 - (e) Aktivieren eines elektromagnetischen Aktuators (44), der mit der Stange (26) gekoppelt ist, um das Gas aus dem Reservoir (14) freizusetzen, indem das Ventil (10) von der geschlossenen Stellung in eine geöffnete Stellung gebracht wird, indem die Stange (26) vom Auslass (18) weg bewegt wird. 50
11. Verfahren zum Betreiben eines Gasventils (10) nach Anspruch 10, wobei nach dem Schritt (d), aber vor dem Schritt (e), die dritte Kraft etwas geringer ist als die Summe der ersten und zweiten Kräfte, um eine Nettokraft wesentlich zu senken, die vom elektromagnetischen Aktuator (44) benötigt wird, um das Ventil (10) in die geöffnete Stellung zu bewegen. 55
12. Verfahren zum Betreiben eines Gasventils (10) nach Anspruch 11, wobei das Aktivieren des elektromagnetischen Aktuators (44) in Schritt (e) ferner das Entladen eines Stroms durch eine elektronische Spule (L1) umfasst, um ein erstes Magnetfeld zu erzeugen, wobei die elektronische Spule (L1) in der Nähe einer Platte (40) angeordnet ist, die mit der Stange (26) fest verbunden ist, wobei das erste Magnetfeld Wirbelströme in der Platte (40) induziert und wobei die Wirbelströme ein zweites Magnetfeld erzeugen, und wobei das zweite Magnetfeld in Bezug auf das erste Magnetfeld entgegengesetzt polarisiert ist, wobei dadurch, dass die ersten und zweiten Magnetfelder entgegengesetzt polarisiert sind, eine Abstoßungskraft erzeugt wird, und wobei die Abstoßungskraft die Platte (40) von der Spule (L1) wegdrückt, um das Ventil (10) von der geschlossenen Stellung in die geöffnete Stellung zu bringen, indem die Stange (26) vom Auslass (18) weg bewegt wird.

Revendications

1. Appareil à valve à gaz à action rapide (10) comprenant :

un réservoir (14) pour contenir un gaz qui possède un orifice de charge (19) pour le remplissage dudit réservoir (14) avec ledit gaz et une sortie (18) pour libérer ledit gaz dudit réservoir (14) ;
une tige (26) logée de façon coulissante dans ledit appareil à valve (10), laquelle tige (26) com-

prend un moyen d'étanchéité disposé pour se mettre en prise avec ladite sortie (18) dudit réservoir (14) pour fermer ledit réservoir (14) quand ledit appareil à valve (10) est en position fermée ;
 5 un actionneur pneumatique (36), un piston (32) dudit actionneur pneumatique (36) étant couplé à ladite tige (26) ;
 une première chambre (60) et une deuxième chambre (62) situées sur des côtés opposés du dit piston (32) dans ledit actionneur pneumatique (36) ;
 10 ledit gaz dans ledit réservoir (14) ayant une première pression (P1) qui exerce une première force sur ladite tige (26) par l'intermédiaire dudit moyen d'étanchéité dans une première direction (56) pour maintenir ladite valve (10) dans ladite position fermée en contrignant ledit moyen d'étanchéité de ladite tige (26) à rester en prise avec ladite sortie (18) ;
 15 une deuxième pression (P2) dans ladite première chambre (60) exerçant une deuxième force sur ledit piston (32) dans ladite première direction (56) pour contraindre ledit moyen d'étanchéité de ladite tige (26) à se mettre en prise avec ladite sortie (18) ;
 20 une troisième pression (P3) dans ladite deuxième chambre (62) exerçant une troisième force sur ledit piston (32) dans une deuxième direction (58), ladite deuxième direction (58) étant opposée à ladite première direction (56), et
 25 un actionneur électromagnétique (44) couplé à ladite tige (26), ledit gaz étant libéré dudit réservoir (14) via ladite sortie (18) quand ledit appareil à valve (10) est en position ouverte, et ladite valve (10) passant de ladite position fermée à ladite position ouverte par l'activation successive desdites actionneurs pneumatique (36) et électromagnétique (44) pour éloigner ladite tige (26) de ladite sortie (18) ;

caractérisé en ce qu'après une activation dudit actionneur pneumatique (36), mais avant une activation dudit actionneur électromagnétique (44), une somme desdites première et deuxième forces est supérieure à ladite troisième force.

2. Appareil à valve à gaz (10) selon la revendication 1, dans lequel ladite troisième force est légèrement inférieure à ladite somme desdites première et deuxième forces pour réduire sensiblement une force nette nécessaire audit actionneur électromagnétique (44) pour faire passer ladite valve (10) de ladite position fermée à ladite position ouverte.
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3. Appareil à valve à gaz (10) selon la revendication 1, dans lequel ledit actionneur électromagnétique (44) comprend :

une bobine électronique (L1) couplée électriquement dans un circuit (46) à une alimentation électrique sous haute tension (VH) et à une capacité (C1) ;
 une plaque conductrice électrique (40) fixée à ladite tige (26) et située près de ladite bobine (L1) quand ladite valve (10) est dans ladite position fermée ; et
 dans lequel ledit actionneur électromagnétique (44) est activé par la décharge d'un courant de ladite capacité (C1) à travers ladite bobine (L1) pour générer un premier champ magnétique dans ladite bobine (L1), ledit premier champ magnétique induisant des courants de Foucault dans ladite plaque (40), lesdits courants de Foucault générant un deuxième champ magnétique, et ledit deuxième champ magnétique étant polarisé à l'opposé dudit premier champ magnétique, ce qui crée une force de répulsion parce que lesdits premier et deuxième champs magnétiques ont une polarité opposée, et ladite force de répulsion repousse ladite plaque (40) et l'écarte de ladite bobine (L1) pour faire passer ladite valve (10) de ladite position fermée à ladite position ouverte en éloignant ladite tige (26) de ladite sortie (18).

4. Appareil à valve à gaz (10) selon la revendication 3, dans lequel ladite plaque (40) est en aluminium.
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5. Appareil à valve à gaz (10) selon la revendication 3, dans lequel ladite bobine (L1) est fabriquée en câble plat.
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6. Appareil à valve à gaz (10) selon la revendication 3, dans lequel ladite source d'énergie à haute tension (VH) applique une tension d'environ 2000 V, ladite capacité (C1) a une capacitance d'environ 150 pF, ladite bobine (L1) a une inductance d'environ 2 mH et ledit circuit (46) a une résistance totale d'environ 1 Ω.
 40
7. Appareil à valve à gaz (10) selon la revendication 3, dans lequel ladite source d'énergie à haute tension (VH), ladite capacité (C1) et ladite bobine (L1) comportent un circuit RLC à atténuation critique.
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8. Appareil à valve à gaz (10) selon la revendication 3, dans lequel ladite plaque (40) est pressée contre ladite bobine (L1) quand ledit appareil à valve (10) se trouve dans ladite position fermée.
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9. Appareil à valve à gaz (10) selon la revendication 8, dans lequel une mince couche de matériau non conducteur est intercalée entre ladite bobine (L1) et ladite plaque (40) quand ladite bobine (L1) et ladite plaque (40) sont pressées ensemble.
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10. Procédé pour faire fonctionner une valve à gaz (10) comprenant les étapes de :

- (a) pressurisation d'une première chambre (60) dans un actionneur pneumatique (36), une deuxième pression (P2) dans ladite première chambre (60) exerçant une deuxième force dans une première direction (56) sur un piston (32) dudit actionneur pneumatique (36), ledit piston (32) étant couplé à une tige (26), pour amener ladite valve (10) en position fermée en contraignant ladite tige (26) à se mettre en prise avec une sortie (18) d'un réservoir (14) de ladite valve à gaz (10) ; 5
- (b) pressurisation d'un réservoir (14) de ladite valve à gaz (10) avec un gaz ayant une première pression (P1) ; 10
- (c) dépressurisation de ladite première chambre (60) dans ledit actionneur pneumatique (36) pour réduire ladite deuxième pression (P2) et ladite deuxième force, ledit gaz dans ledit réservoir (14) exerçant une première force en raison de ladite première pression (P1) dans ladite première direction (56) sur ledit piston (32) pour maintenir ladite valve (10) dans ladite position fermée en contraignant ladite tige (26) à rester en prise avec ladite sortie (18) ; 15
- (d) pressurisation d'une deuxième chambre (62) dans ledit actionneur pneumatique (36) située d'un côté dudit piston (32) opposé à ladite première chambre (60), une troisième pression (P3) dans ladite deuxième chambre (62) exerçant une troisième force sur ledit piston (32) dans une deuxième direction (58) opposée à ladite première direction (56) desdites première et deuxième forces, ledit piston (32) transmettant ladite troisième force à ladite tige (26), et une somme desdites première et deuxième forces étant supérieure à ladite troisième force ; et 20
- (e) activation d'un actionneur électromagnétique (44) couplé à ladite tige (26) pour libérer ledit gaz dudit réservoir (14) en faisant passer ladite valve (10) de ladite position fermée à une position ouverte en éloignant ladite tige (26) de ladite sortie (18). 25

11. Procédé pour faire fonctionner une valve à gaz (10) selon la revendication 10, dans lequel, après l'étape (d) mais avant l'étape (e), ladite troisième force est légèrement inférieure à ladite somme desdites première et deuxième forces afin de réduire sensiblement une force nette nécessaire audit actionneur électromagnétique (44) pour faire passer ladite valve (10) dans ladite position ouverte. 30

12. Procédé pour faire fonctionner une valve à gaz (10) selon la revendication 11, dans lequel l'activation du dit actionneur électromagnétique (44) dans l'étape 35

(e) comprend en outre la décharge d'un courant à travers une bobine électronique (L1) pour créer un premier champ magnétique, ladite bobine électronique (L1) étant située près d'une plaque (40) qui est fixée à ladite tige (26), ledit premier champ magnétique induisant des courants de Foucault dans ladite plaque (40), et lesdits courants de Foucault générant un deuxième champ magnétique, et ledit deuxième champ magnétique étant polarisé à l'opposé dudit premier champ magnétique, une force de répulsion étant créée parce que lesdits premier et deuxième champs magnétiques sont de polarité opposée, et ladite force de répulsion repoussant ladite plaque (40) de ladite bobine (L1) pour faire passer ladite valve (10) de ladite position fermée à ladite position ouverte en contraignant ladite tige (26) à s'écartez de ladite sortie (18). 40

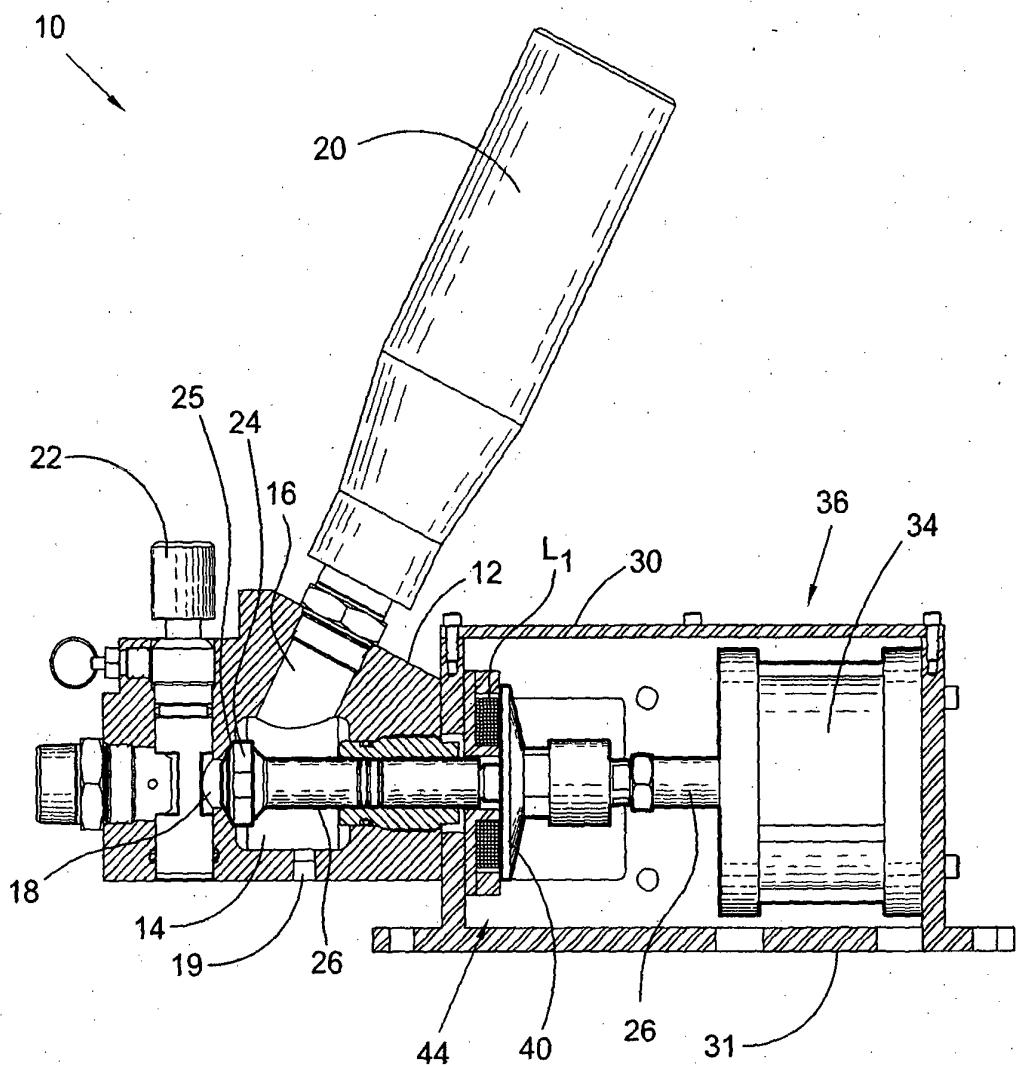


Fig. 1

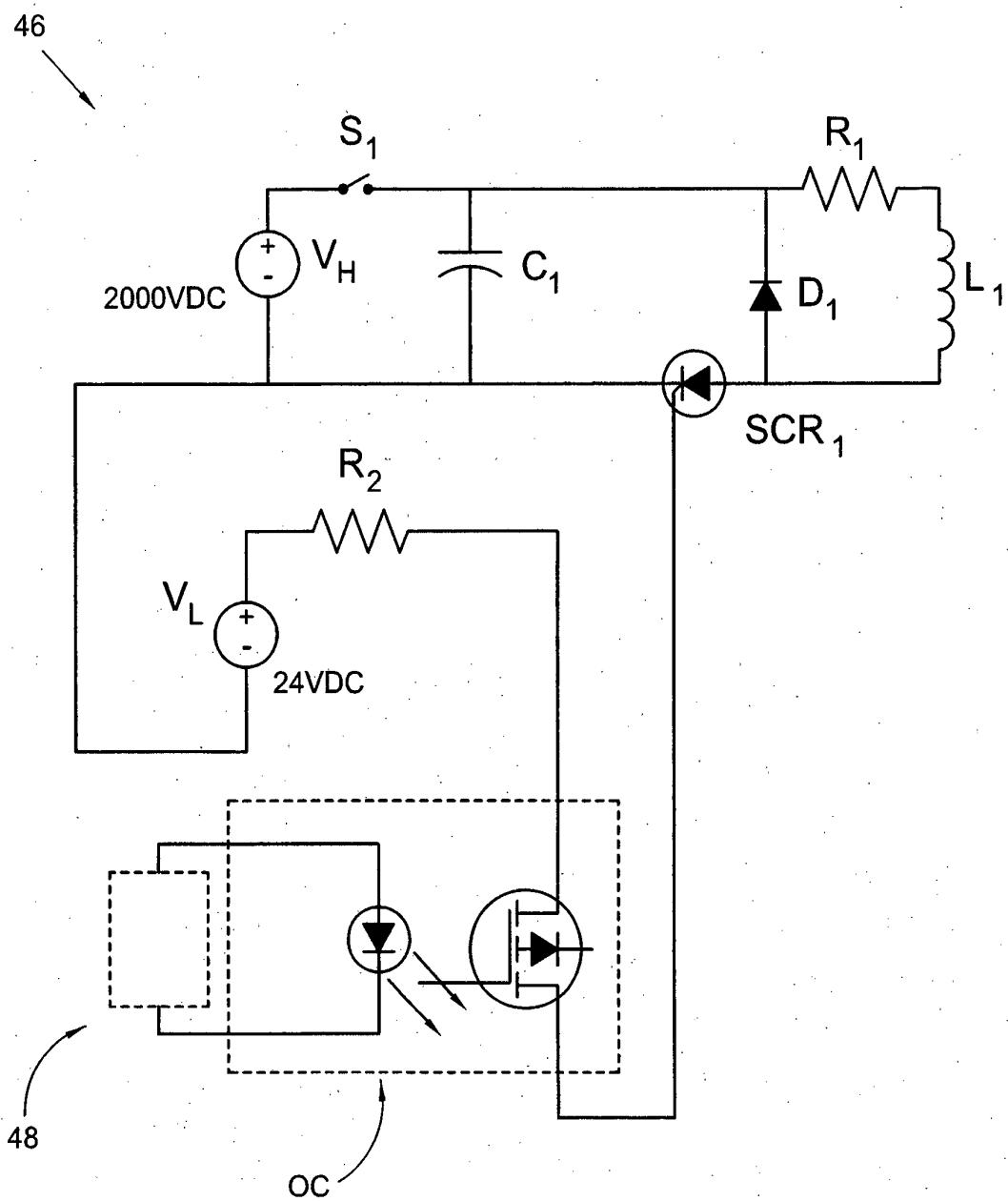


Fig. 2A

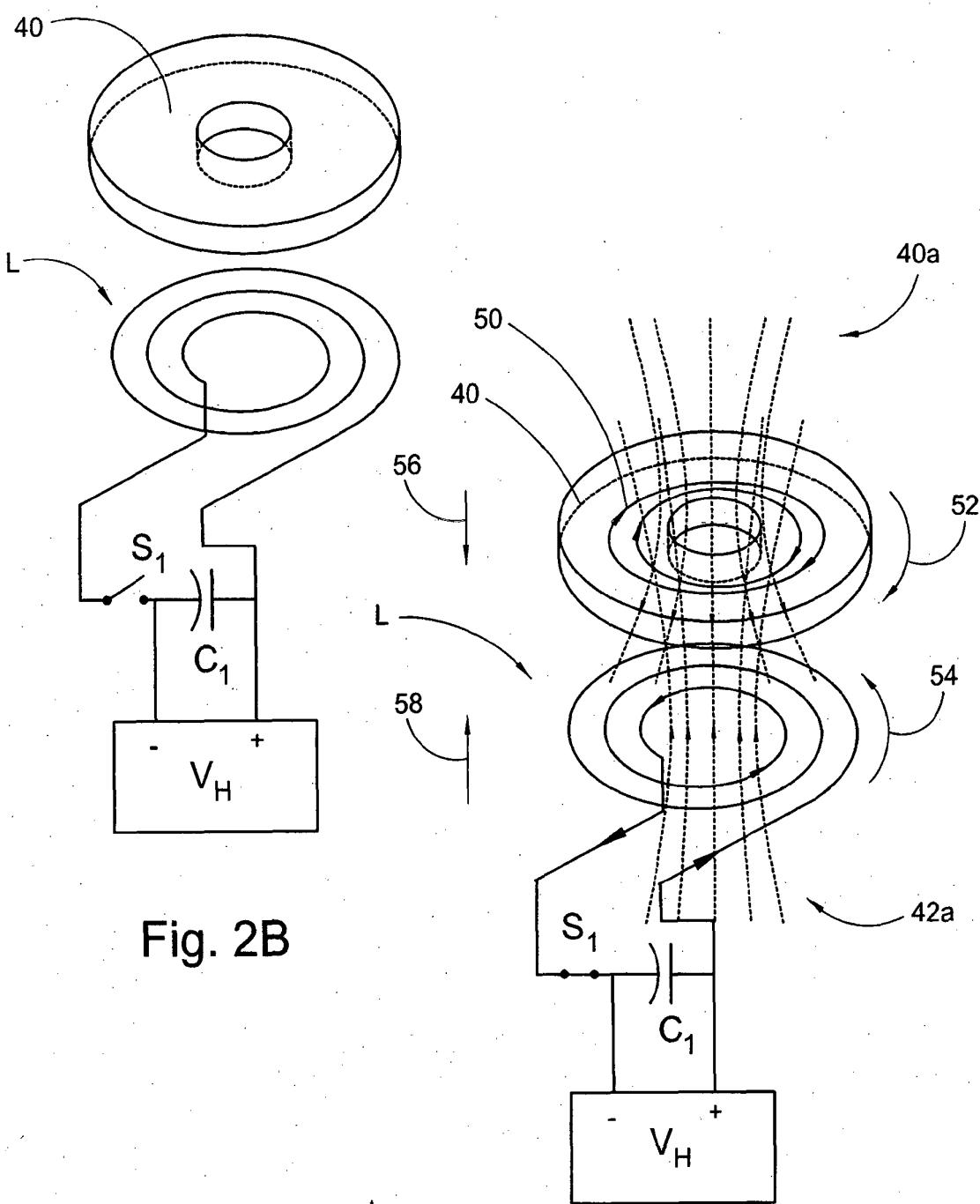
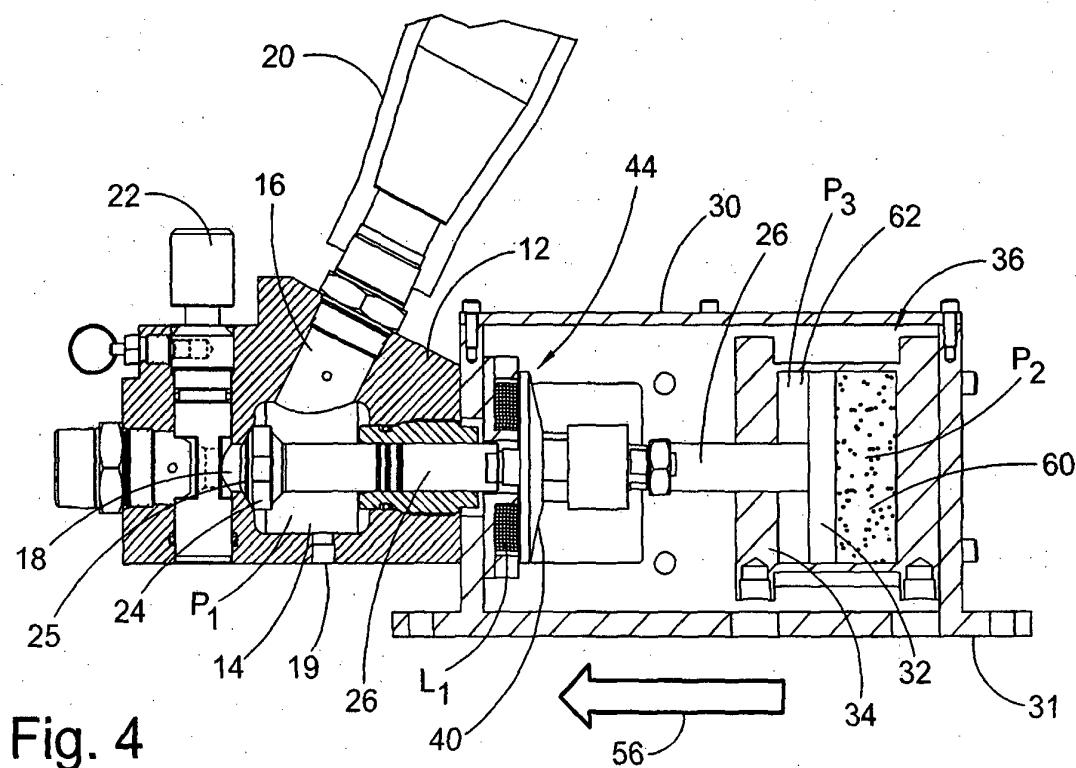
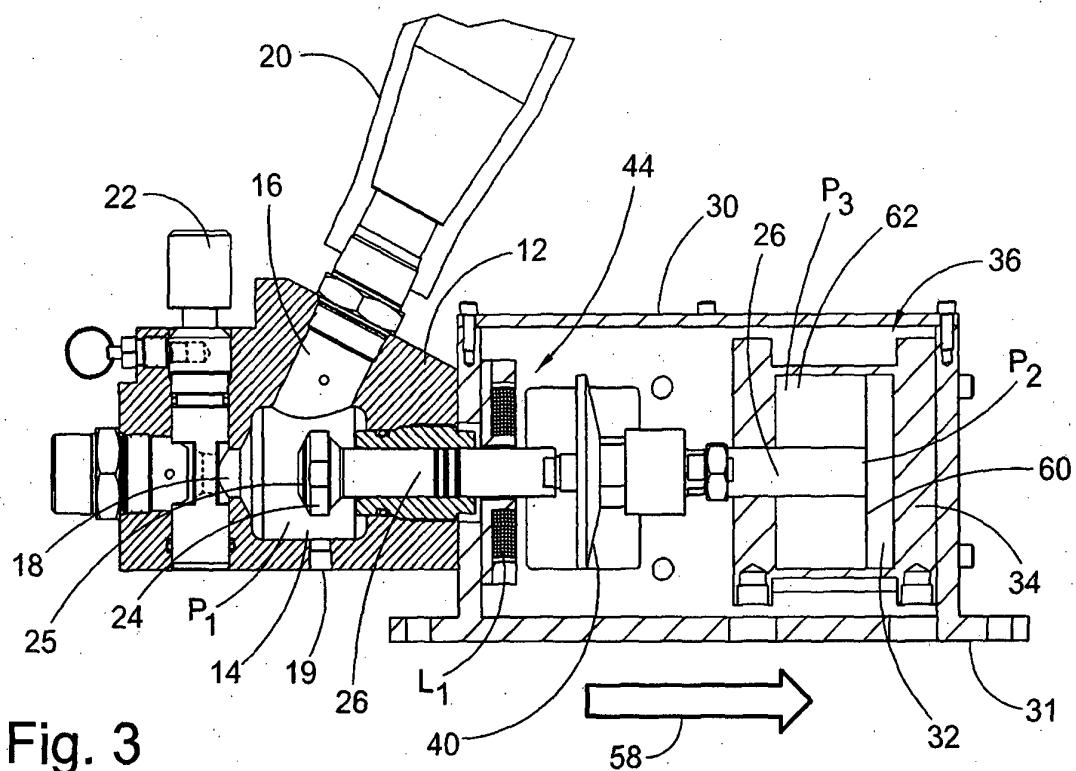


Fig. 2B

Fig. 2C



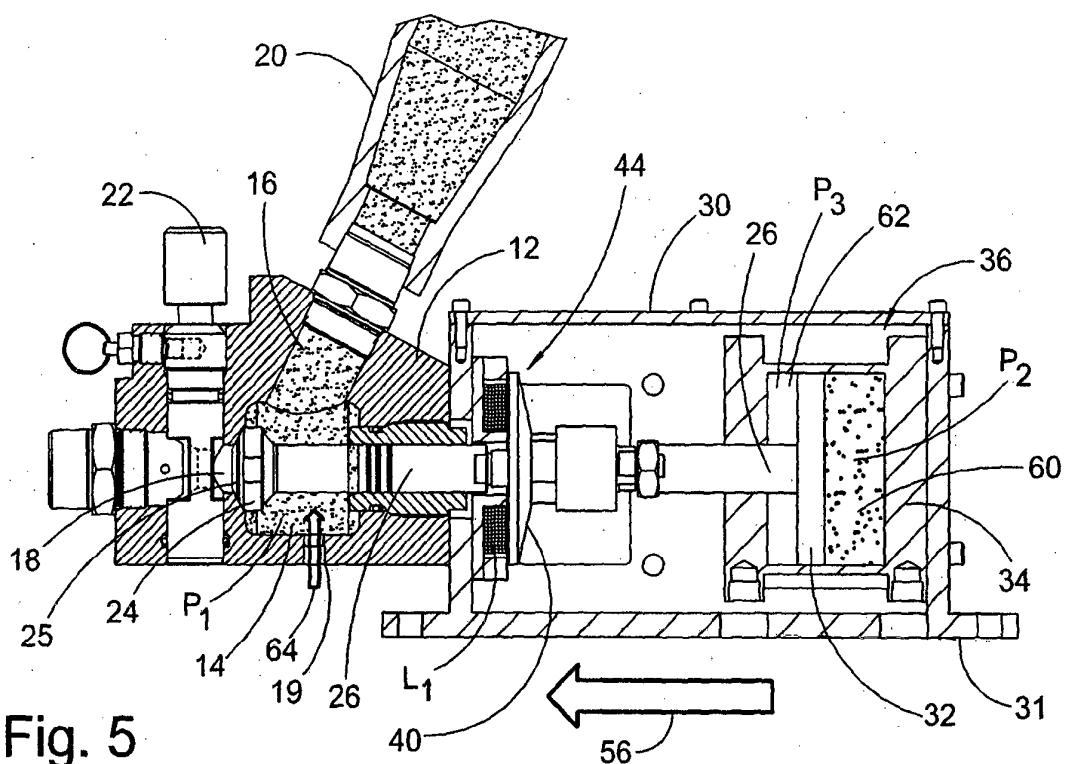


Fig. 5

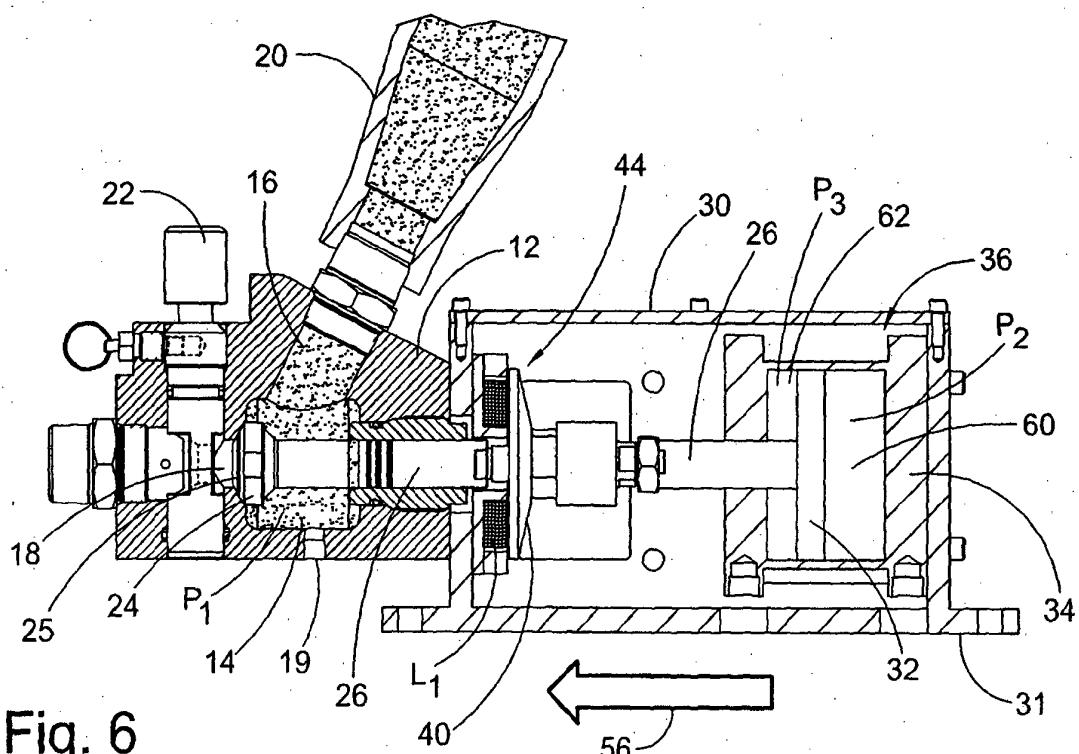


Fig. 6

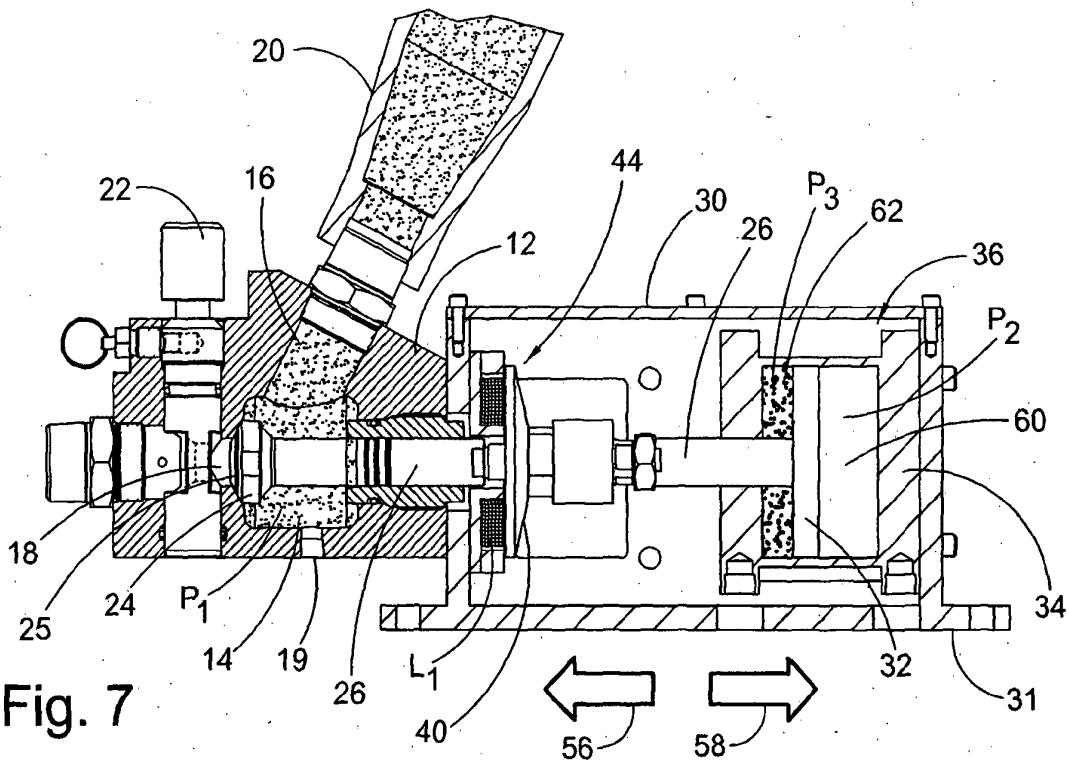


Fig. 7

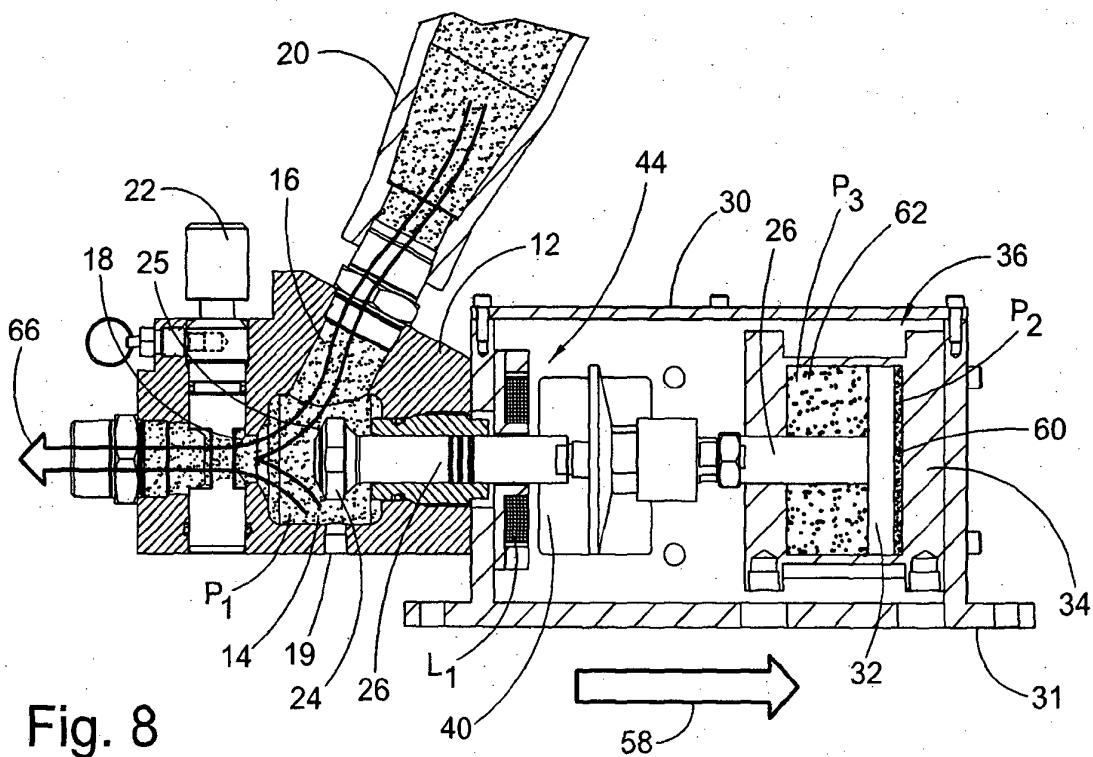


Fig. 8

REFERENCES CITED IN THE DESCRIPTION

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